



# AFC

high accuracy micro assembly cell

**MORE THAN PRECISION** 

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AFC Precision of Assembly +/- 0.5 μm



- Modular machine concept
- +/- 0.5µm placement accuracy
- Flip-chip option
- Assembly of chip and micro-optics
  WDM, optoelectronic components, micro-lenses, micro- mechanics
- Die Sorting
- Wafer mapping
- Epoxy stamping and dispensing
- Eutectic bonding via diode-laser or heatingplate
- UV-Curing option
- Dispensing option
- Active / Passive alignment
- Active bond-force -control
- Postbond inspection





## Laser and Eutectic Soldering

- Adjustable heating courses with high soldering temperatures (up to 400° for AuSn-solder)
   Shortest coldering time (.12)
- Shortest soldering time (<1s)
- Best yield and high quality by repeatability of laser soldering



### Technical Concept

- Relative positioning
- Positioning substrate to camera coordinate system X,Y,Phi
- Positioning chip to camera coordinate system X,Y,Phi



## Precision Components

- Vibration damping due granite base design
- High precision stages driven by AC motors
- Precision vision system with high resolution CCD-cameras
- High accuracy bondhead with piezo systems
- Flip-Chip-Unit
- Wafer, Wafflepack, Gel-Pak



### Active/Passive alignment

- Permanent observation of the components through stationary high resolution cameras
- Controlling the position during alignment and setting process
- Die alignment to active components (e.g. microlenses to energized laserchip)
- Die alignment to fiducial marks (e.g. V-groove)
- Flipped Die alignment through up- and down-side correlation



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## **Technical Informations**

Gerneral	
control	multi-axis-controller
operating system	Windows XP
programming	keyboard and graphic display
operator interface	menu driven. English
data transfer	ethernet TCP/IP_electronic connection: 10
	Base T 10 Mhit/s
Fauinment	
BUNDHEAD TRANSFER S	YSIEM
TUTICLIOIT	moves bondnead from source side (chip side)
and the second	to destination side (substrate side)
coarse X axis positioning	linear motor driven, nigh velocity and accelera-
	tion; noncontact linear encoder, resolution 1µm
Z axis	AC servo drive, noncontact linear encoder,
	resolution 1µm
DESTINATION TABLE FOR	SUBSTRATE
XY axis	AC or stepper motor driven, open-frame
	design (optional linear motor)
range of XY axis	210 x 210 mm
optinal: rotations Axis	stepper motor-driven, 360°,
	resolution 0.01°
SOURCE TABLE FOR WAF	ER
XY axis	AC or stepper motor driven, open-frame
	design (optional linear motor)
range of XY axis	210 x 210 mm
optional: rotations axis	stepper motor-driven, 360°,
	resolution 0.01°
CAMERA AXIS	
Z axis (focussing)	AC servo drive, resolution 1 µm
ΒΟΝΠΗΕΔΠ	
function	design for active adjustment: high accuracy
	nositioning: hondforce controlling
XY axis	niezo driven: resolution 0 1um:
	range 400um x 400um
rotation axis	360° resolution 0.001°
hond force	programmable, standard working area 3
bond force	-100 g: resolution 0.5 g (other working area
touch sensor	determines first mechanical contact
	between chin and substrate
EIECTION SYSTEMS	between thip and substrate
neeule systems	single of multi-needle system according to
election needlo type	0.7 mm chaft diamotor 17.0 mm long redius
ejection needle type	0.7 mm smart utarrieter, 17.0 mm long, radius
signation beight	25µm, other needles on request
ejection neight	programmable neight and delays
ejection speed	programmable
Lasersystem	
function	tor fast eutectic bonding with controlled heat
technique	tiber-coupled high power laser with focussing
	optic
max. output power	45 W or 75 W
center wavelength	808 nm (+-10%) other wavelength on request
temperature	programmable, range: up to 400° C; online
	measurement phyrometer
pulsetime	programmable, range: 0.01s to 9.99s; resolu-
	tion: 10ms
Image Recognition	
vision System	COGNEX
focussing	programmable; optional autofocus function
	during programming
recognition methods	standard vision tools: special filter for micro

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pattern recognition

stuctures

programmable windows and models



SOURCE CAMERA (MATERIAL SIDE E.G. LASERCHIP)	
depth of field	+/- U.I IIIIII
CCD camera crip size	I/2, Uptional I/3, 2/3
magnification	SX; Utiler magnification on request
TIEID OT VIEW	approx. 1,5 x 1 mm <sup>2</sup>
pixel resolution	approx. 1,7 µm/Pixel at 1/2" CLD-chip
illumination	coaxiai lighting; LED or haiogen
DESTINATION LAMERA (SUBSTRAT SIDE)	
depth of field	+/- IUµm
CCD camera chip size	1/2", optional 1/3", 2/3"
magnification	TUx; other maginification on request
field of view /FOV/Pixel	approx. 0,64 x 0,48 mm <sup>2</sup>
resolution	approx. 0,8 µm/Pixel at 1/2" CLD-chip
illumination	coaxial lighting; LED or halogen
UPWARD CAMERA FOR denth of field	+/- 10um
CCD camera chin size	1/2", ontional 1/3", 2/3"
magnification	10x: other maginification on request
field of view /FOV/ Pixel	annrox $0.64 \times 0.48 \text{ mm}^2$
resolution	approx 0.8 µm/Pixel at 1/2" (CD-chin
illumination	coaxial lighting: LED or halogen
	countering, 220 of herosen
Dimensions/ Power ratings	
size (WxDxH), weight	1400 x 1200 x 1700 mm, 1800 kg
vacuum	- 0.8 bar, Throughput: 3 m³/h
compressed air	5 bar dry and oilfree air
nitrogen	1 bar
electrical power ratings	distribution voltage: 400 V opt. 230 V/115V
ambient temperature	18 to 25 °C
relative humidity	non-condensing
Capacity Ratings	
module-specific cycle	>= 10.0 s depending on configuration and
time	application
module-specific cycle	>= 13 s depending on configuration and application
time for flip-chip process	
throughput	
machine availability	up to 360 components/h device dependent >95%
accuracy	1 O E um@2c



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